

Temposonics®

Magnetostrictive, Absolute, Non-contact
Linear-Position Sensors

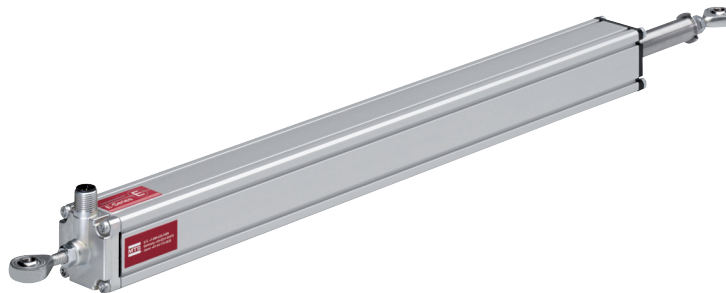


E-Series Model ER

Analog and Digital-Pulse (Start/Stop) Outputs

Document Part Number:
550996 Revision E

Data Sheet



**Model ER position sensor-
Stroke Length: 50 mm to 1500 mm (2 in. to 60 in.)**

FEATURES

- Linear, Absolute Measurement
- Non-Contact Sensing Technology
- Linearity Deviation Less Than 0.02% F.S.
- Repeatability Within 0.001% F.S.
- Two Outputs Available:
 - Analog (Voltage/Current) Forward or Reverse Acting
 - Digital-Pulse Output (Start/Stop)
- Simple Sensor Parameter Upload (for Start/Stop)
- Stroke Length Range: 50 mm to 1500 mm (2 in. to 60 in.)
- Internal Electronics are Sealed for IP67 Ingress Protection
- EMI Shielded and CE Certified

BENEFITS

- Rugged, Cost Effective, Precise and Durable Non-wear Alternative to Linear Potentiometers
- Extendable and Retractable Dual Rod Ends
- The Magnet is Contained and Protected Inside The Sensor Housing
- Over Voltage Protection to 36 Vdc and Polarity Protection up to -30 Vdc

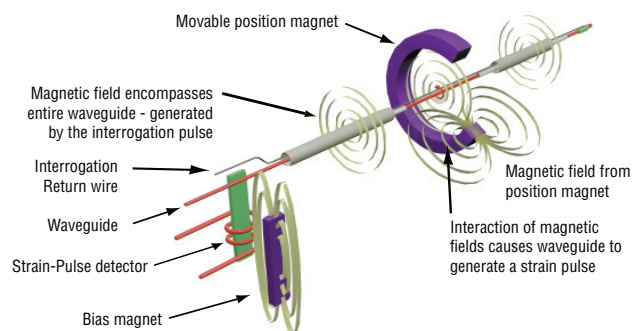
APPLICATIONS

- Continuous Operation In Harsh Industrial Conditions

TYPICAL INDUSTRIES

- Factory Automation
- Woodworking and Metal Forming
- Material Handling and Packaging

Time-based Magnetostrictive position sensing principle



Benefits of Magnetostriction

Temposonics linear-position sensors use the time-based magnetostrictive position sensing principle developed by MTS. Within the sensing element, a sonic-strain pulse is induced in a specially designed magnetostrictive waveguide by the momentary interaction of two magnetic fields. One field comes from a movable permanent magnet that passes along the outside of the sensor. The other field comes from an “interrogation” current pulse applied along the waveguide. The resulting strain pulse travels at sonic speed along the waveguide and is detected at the head of the sensing element.

The position of the magnet is determined with high precision and speed by accurately measuring the elapsed time between the application of the interrogation pulse and the arrival of the resulting strain pulse with a high-speed counter. The elapsed time measurement is directly proportional to the position of the permanent magnet and is an absolute value. Therefore, the sensor's output signal corresponds to absolute position, instead of incremental, and never requires recalibration or re-homing after a power loss. Absolute, non-contact sensing eliminates wear, and guarantees the best durability and output repeatability.

All specifications are subject to change. Contact MTS for specifications and engineering drawings that are critical to your application. Drawings contained in this document are for reference only. Go to <http://www.mtssensors.com> for the latest product documentation and related media.

E-Series Model ER Sensor, Analog and Start/Stop Outputs

Product Overview and Specifications

MTS Sensors continues to establish new performance standards for low-cost, fully-industrial, durable position sensors using the widely preferred magnetostrictive technology. This principle for accurate and non-contact measurement of linear-position sensing was developed 30 years ago by MTS and is used with outstanding success in a large variety of industrial applications.

The innovative Temposonics model ER sensor brings proven benefits of magnetostrictive feedback to the versatile rod-and-cylinder sensor package.

It is ideal for demanding industrial applications where high performance non-contact feedback is essential for maximum productivity and overall reliability. The model ER sensor's rod-and-cylinder design has a rod that can extend from the sensor housing. As the rod is extended and retracted, the sensing magnet remains completely contained and protected at all times, ensuring reliable sensor performance in the toughest industrial environments.

Product specifications

Parameters	Specifications	Parameters	Specifications
OUTPUT		ENVIRONMENTAL	
Measured output variables:	Position	Operating conditions:	Operating temperature: -40 °C (-40 °F) to 75 °C (167 °F) Relative humidity: 90% no condensation Ingress protection: IP 67 <i>(when mating connector is correctly fitted)</i>
Resolution:	Analog: Infinite (restricted by output ripple) Start/Stop: 0.1, 0.01 and 0.005 mm (controller dependent)	EMC test:	Electromagnetic emission: EN 61000-6-4, CISPR 16 Electromagnetic susceptibility: EN 61000-6-2, EN 61000-4-2/3/4/6, CE qualified
Linearity deviation:	< ± 0.02% full stroke (minimum ± 60 µm)	Shock rating:	100 g (single hit)/ IEC standard EN 60068-2-27
Repeatability:	< ± 0.001% full stroke (minimum ± 5 µm)	Vibration rating:	10 g/10 to 2000 Hz, IEC standard EN 60068-2-6 (resonance frequencies causing excess of 10 g are excluded)
Outputs:	Analog (voltage or current) Voltage: 0 to 10 Vdc and 10 to 0 Vdc or Two outputs: 0 to 10 Vdc and 10 to 0 Vdc (controller input resistance RL ≥ 5k Ohm) Current: 4 to 20 mA or 20 to 4 mA (Controller input resistance RL ≤ 500 Ohm) Digital-pulse (Start/Stop): RS-422 differential signal Serial parameter upload available for: Measuring range, offset, gradient, status and manufacturer number	WIRING	Connection types: Analog output: 5-pin (M12) male integral connector Start/Stop output: 8-pin (M12) male integral connector
Stroke length:	Range: 50 mm to 1500 mm (2 in. to 60 in.)	ROD-AND-CYLINDER STYLE SENSOR	
ELECTRONICS		Sensor rod:	Aluminum
Operating voltage:	+24 Vdc nominal: -15% or +20% Polarity protection: up to -30 Vdc Over voltage protection: up to 36 Vdc Current drain: Analog: 50 - 140 mA Start/Stop: 50 - 100 mA <i>(Stroke length dependent)</i> Dielectric withstand voltage: 500 Vdc (DC ground to machine ground)	Sensor housing:	Aluminum
		Mounting options:	Adjustable mounting clamps or dual rod ends

Outputs

ANALOG (VOLTAGE/CURRENT) OUTPUTS

Analog outputs include voltage (0 to 10 Vdc forward or reverse acting), and current (4 to 20 mA forward or reverse acting). Since the outputs are direct, no signal conditioning electronics are needed when interfacing with controllers or meters (see 'Figure 1').

Analog output voltages ranges:

- 0 to 10 Vdc
- 10 to 0 Vdc
- 0 to 10 Vdc and 10 to 0 Vdc
- 4 to 20 mA
- 20 to 4 mA

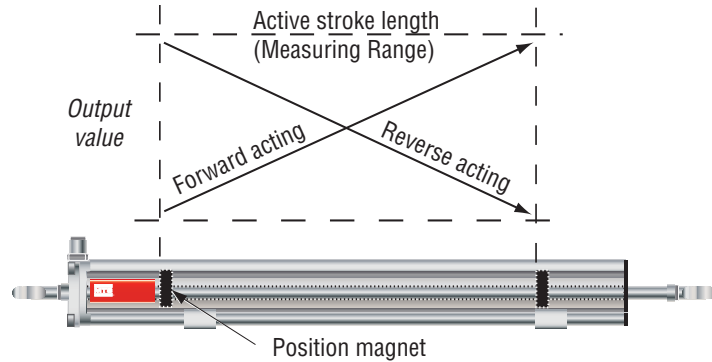


Figure 1. Analog Output signals

DIGITAL START/STOP OUTPUT

The Tempsonics E-Series Model ER Start/Stop output sensors require a start signal from a controller or interface module to initiate the measurement cycle. The sensor generates a stop signal at the end of the measurement cycle that is used to stop the controller's counter clock.

The elapsed time between the Start and Stop signals is directly proportional to the magnet's position along the active stroke length. The controller can calculate the absolute position of the magnet from the time value and the sensor's unique gradient value (inverse of the speed for the sonic pulse traveling in the sensor's waveguide). (see 'Figure 2').

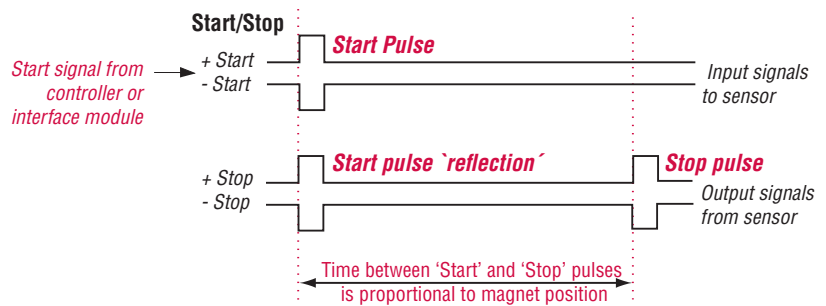


Figure 2. Start/Stop output signals (RS-422 differential pairs)

Communication and programmability

SENSOR PARAMETER UPLOAD FEATURE

For applications using smart sensor interfaces, the Model ER sensor with Start/Stop output (Option **R3**) comes with the ability to perform sensor parameter uploads. This feature replaces the task of entering sensor data manually, saving time and preventing possible entry errors during start-up or for system maintenance.

Note: Start/Stop output (option R3)

When the sensor parameter upload feature is not activated the Start/Stop output (Option **R3**) remains fully compatible with the Start/Stop output (Option **R0**) used in the previous generation E-Series sensor family.

The upload feature supports the following sensor parameters:

- Measuring range
- Offset
- Gradient - (Shown as speed of the sonic-strain pulse (m/s) or inverse speed (μs/in.))
- Status
- Manufacturer number

The sensor's specific parameters can be retrieved by the controller and interface module at any time, via the sensor's Start/Stop signal lines.

The sensor parameter upload feature requires a customer supplied RS-422 interface. The data format is serial, 4800 Baud, 8-bit data length. Please contact the factory for additional parameter upload protocol details.

E-Series Model ER Sensor, Analog and Start/Stop Outputs

Sensor Dimensions and Mounting

Model ER rod-and-cylinder sensor dimension references

Drawings are for reference only, contact applications engineering for tolerance specific information.

A robust aluminum extrusion forms the sensor housing containing the sensor rod, magnet, sensing element and electronics. The permanent magnet is mounted on a sliding carrier attached to the end of the rod. As the rod moves in and out, the magnet travels above the sensing element inside the sensor housing.

MODEL ER ROD-AND-CYLINDER SENSOR

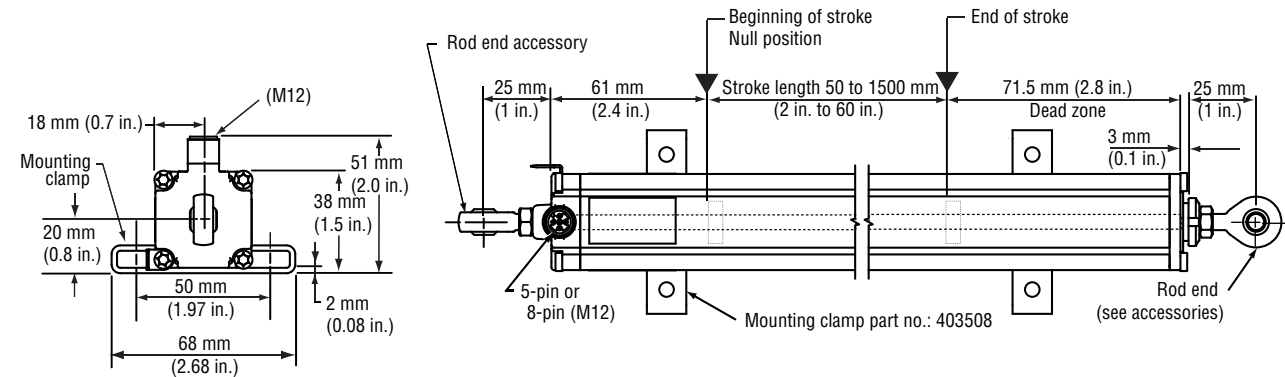


Figure 3. E-Series model ER rod-and cylinder sensor dimension reference


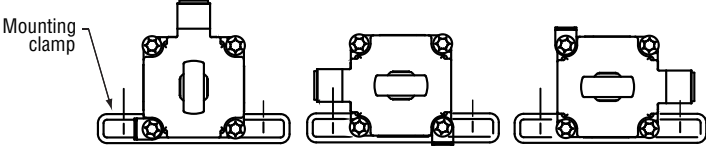
Sensor mounting (Model ER)

SENSOR MOUNTING CLAMPS

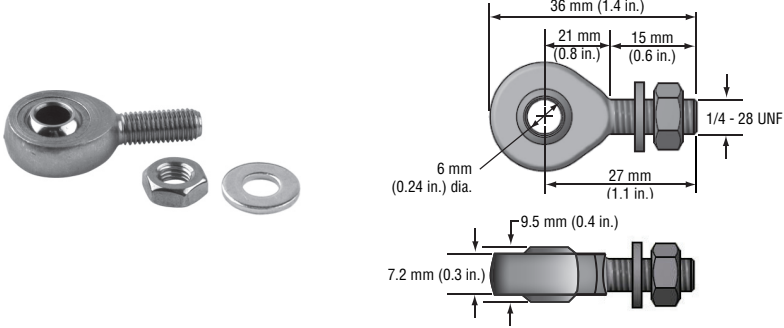
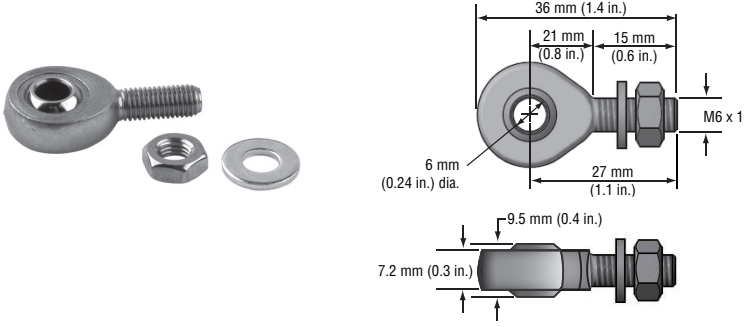
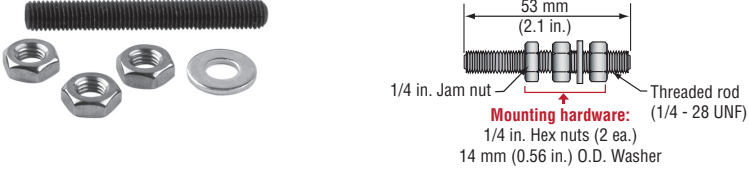
The E-Series model ER sensor is mounted onto the machine with moveable mounting clamps. Grooves for mounting clamps are available on three sides of the sensor housing, allowing versatile mounting orientations for the sensor's connector and extension cable. The rod is then attached to the moving machine part.

Optional rod ends can be used to simplify sensor installation design and facilitate articulated motion sensing. Using dual rod ends the model ER sensor can be mounted between two independent moving points, such as swinging door applications. Please note for model ER sensors having stroke lengths over 750 mm (30 in.) only the first 90% of the stroke length can be used for articulated type applications when the weight of the sensor is supported only by rod ends.

Notes:	
1.	Mounting clamps are ordered separately. Two mounting clamps, (part number 403508) are required for stroke lengths up to 750 mm (30 in.). A least one additional mounting clamp is required for longer stroke lengths.
2.	MTS recommends using 10-32 cap screws (customer supplied) at a maximum torque of 44 in. lbs. when fastening mounting clamps.

Model ER sensor mounting and installation reference	Mounting method	Part number
	Mounting clamp Sensor mounting for sensor model ER	403508
	Three possible mounting configuration using mounting clamp and screws	Mounting clamp, part number 403508

E-Series Model ER Sensor, Analog and Start/Stop Outputs
Sensor Mounting

Model ER sensor mounting and installation reference	Mounting method	Part number
	Rod end US customary measurement Optional, male 1/4 - 28 threads	254235
	Rod end Metric measurement Optional, male M6 threads	254210
	Stud end Optional mounting hardware kit Hex nuts (2 pcs.), jam nut and washer	251975

E-Series Model ER Sensor, Analog and Start/Stop Outputs
Connections and Wiring

Connections and wiring (Model ER)

SENSOR INTEGRAL CONNECTOR (D34 AND D84) PINOUT/WIRE COLOR CODES

The E-Series model ER sensor connects directly to a controller or interface module with the standard male, 5-pin or 8-pin integral connector and an extension cable as described in ‘Table 1’ and ‘Table 2’ below.

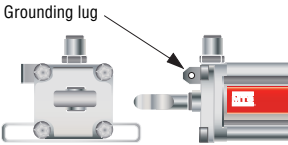


Figure 4. Grounding lug location.

Attention:

The sensors aluminum housing has an anodic coating which prevents the sensor’s mounting clamps from providing the appropriate grounding. A grounding lug (see ‘Figure 4’) is provided near the connector end of the sensor for a convenient connection to earth ground. The appropriate grounding of the cable shield is also required at the controller end.



Integral D34 connector (male) as viewed from the end of the sensor

Pin no.	Extension Cable Wire color	Signal/Function Analog outputs
1	Brown	+24 Vdc
2	White	Output signal
3	Blue	DC ground (for power return)
4	Black	2nd Output signal (optional)
5	Green	Ground for signal return

Table 1. Integral D34 sensor connector
(mates with cable connectors 370618 and 370619)




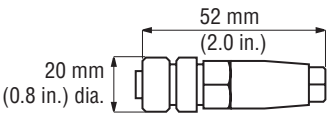

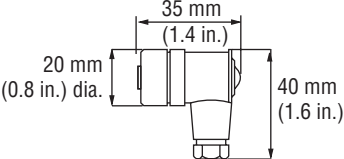
Integral D84 connector (male) as viewed from the end of the sensor

Pin no.	Extension cable wire color	Signal/function Start/Stop outputs
1	White	(+) Start
2	Brown	(-) Start
3	Green	(+) Stop
4	Yellow	(-) Stop
5	Gray	No connection
6	Pink	No connection
7	Blue	+24 Vdc
8	Red	DC ground (for power return)


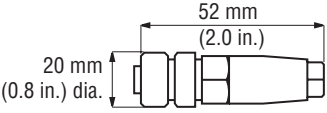

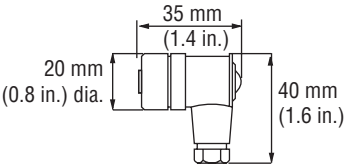
Table 2. Integral D84 sensor connector
(mates with cable connectors 370671 and 370672)

E-Series Model ER Sensor Cable Connector Options (D34 and D84)


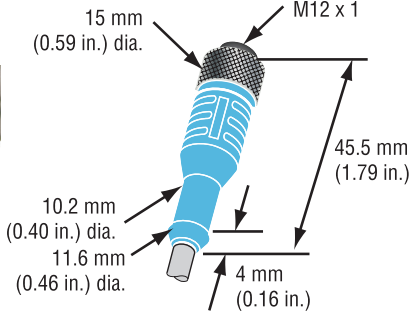
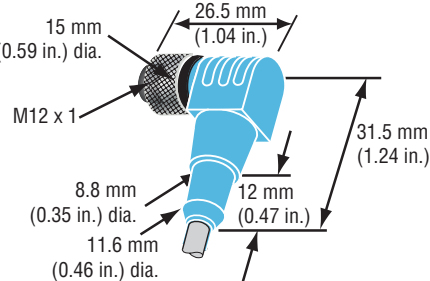

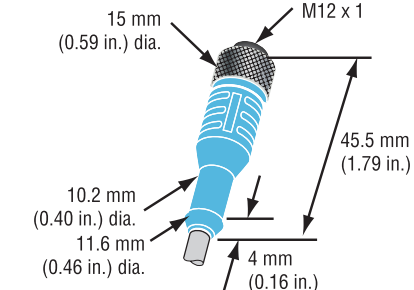
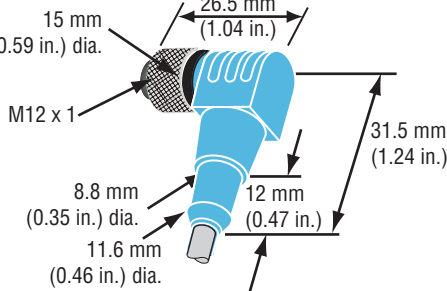
MATING CABLE CONNECTOR OPTIONS FOR (D34) CONNECTOR TYPES *(Photo and drawing dimensions are for reference only)*

Connector and dimensions	Description	Part number
 	Female cable connector, straight exit (Field installable) 5-Pin (D34) Mates with standard male (M12) integral connector Termination: Screw terminals Cable gland: PG9 for 6-8 mm dia. cable Ingress protection: IP67	370618
 	Female cable connector, 90° exit (Field installable) 5-Pin (D34) Mates with standard male (M12) integral connector Termination: Screw terminals Cable gland: PG9 for 6-8 mm dia. cable Ingress protection: IP67	370619

MATING CABLE CONNECTOR OPTIONS FOR (D84) CONNECTOR TYPES *(Photo and drawing dimensions are for reference only)*

Connector and dimensions	Description	Part number
 	Female cable connector, straight exit (Field installable) 8-Pin (D84) Mates with standard male (M12) integral connector Termination: Screw terminals Cable gland: PG9 for 6-8 mm dia. cable Ingress protection: IP67	370671
 	Female cable connector, 90° exit (Field installable) 8-Pin (D84) Mates with standard male (M12) integral connector Termination: Screw terminals Cable gland: PG9 for 6-8 mm dia. cable Ingress protection: IP67	370672

E-Series Model ER Sensor
M12 Cord Sets and Adapter Cable Options

M12 CORD SETS AND (M16) ADAPTER CABLE OPTIONS <i>(Photo and drawing dimensions are for reference only)</i>		
Cord set and dimensions	Description	Part number
  <p>15 mm (0.59 in.) dia. M12 x 1 45.5 mm (1.79 in.) 10.2 mm (0.40 in.) dia. 11.6 mm (0.46 in.) dia. 4 mm (0.16 in.)</p>	<p>M12 Cord set, female connector, Straight exit 5-Pin (M12) mates with standard male (D34) integral connector Ingress protection: IP67 Cable: 5 m, PUR jacket, shielded, pigtail end</p>	370673
<p>(Image not available)</p>  <p>15 mm (0.59 in.) dia. M12 x 1 26.5 mm (1.04 in.) 31.5 mm (1.24 in.) 8.8 mm (0.35 in.) dia. 12 mm (0.47 in.) 11.6 mm (0.46 in.) dia.</p>	<p>M12 Cord set, female connector 90° exit 5-Pin (M12) mates with standard male (D34) integral connector Ingress protection: IP67 Cable: 5 m, PUR jacket, shielded, pigtail end</p>	370675
  <p>15 mm (0.59 in.) dia. M12 x 1 45.5 mm (1.79 in.) 10.2 mm (0.40 in.) dia. 11.6 mm (0.46 in.) dia. 4 mm (0.16 in.)</p>	<p>M12 Cord set, female connector, straight exit 8-Pin (M12) mates with standard male (D84) integral connector Ingress protection: IP67 Cable: 5 m, PUR jacket, shielded, pigtail end</p>	370674
<p>(Image not available)</p>  <p>15 mm (0.59 in.) dia. M12 x 1 26.5 mm (1.04 in.) 31.5 mm (1.24 in.) 8.8 mm (0.35 in.) dia. 12 mm (0.47 in.) 11.6 mm (0.46 in.) dia.</p>	<p>M12 Cord set, Female, Connector 90° Exit 8-Pin (M12) mates with standard male (D84) integral connector Ingress protection: IP67 Cable: 5 m, PUR jacket, shielded, pigtail end</p>	370676
Adapter cable and dimensions	Description	Part number
<p>(Image not available)</p>	<p>Adapter cable 5-Pin female (M12) connector, straight exit to 6-pin male D60 (M16) connector, straight exit Ingress protection: IP67</p>	254206
<p>(Image not available)</p>	<p>Adapter cable 8-Pin female (M12) connector, straight exit to 6-pin male D60 (M16) connector, straight exit Ingress protection: IP67</p>	254207

E-Series Model ER Sensor, Analog and Start/Stop Outputs

Sensor Ordering Information

Use the order matrix below to configure your Model ER sensor order number.

E	R							D			1			
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15

SENSOR MODEL

ER = E-Series model ER position sensor

HOUSING STYLE

S = Inside thread 1/4 - 28 at end of rod (For model ER sensors using US customary stroke length measurement)

M = Inside thread M6 at end of rod (For model ER sensors using metric stroke length measurement)

STROKE LENGTH

____ **M** = Millimeters (Encode in 25 or 50 mm increments) as indicated in 'Stroke length notes' below.

____ **U** = Inches (Encode in 1 or 2 in. increments) as indicated in 'Stroke length notes' below.
(Digit for tenths of inches is always '0')

Stroke length Notes:

Stroke length ranges:

M = 50 to 1500 mm (Preferred stroke lengths are: 75,100, 150, 200, 300, 400, 500, 600, 750, 1000 and 1250 mm)

U = 2 to 60 in. (Preferred stroke lengths are: 3, 6, 9, 12, 15, 18, 22, 24, 30, 42, 48 and 54 in.)

The increment size between standard stroke lengths vary as shown below:

Stroke length (mm)	Ordering increment
≤ 500 mm	25 mm
> 500 mm and ≤ 1500 mm	50 mm
Stroke length (IN)	Ordering increment
≤ 20 in.	1 in.
> 20 in. and ≤ 60 in.	2 in.

SENSOR CONNECTION TYPES

D34 = 5-Pin (M12), male, (Analog output)

D84 = 8-Pin (M12), male, (Start/Stop output)

INPUT VOLTAGE

1 = + 24 Vdc (+20%, -15%), standard

OUTPUT (2 or 3 digit code defined by output option selected below)

VOLTAGE

V01 = 0 to 10 Vdc

V11 = 10 to 0 Vdc

V03 = 0 to 10 Vdc and 10 to 0 Vdc (2 output channels)

CURRENT

A01 = 4 to 20 mA

A11 = 20 to 4 mA

START/STOP

R3 = Start/Stop with sensor parameters upload function

Start/Stop output (Option **R3**) is fully compatible with the Start/Stop output (Option **RO**) used in the previous generation E-Series sensors.



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